

FORM HDP-1449 (Based on Form PTO-1449)

ATTORNEY DOCKET NO.

SERIAL NO.

2115-001857/CPB

10/672,290

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INFORMATION DISCLOSURE CITATION

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Sheet 1 of 5

APPLICANT

Johann Borenstein et al.

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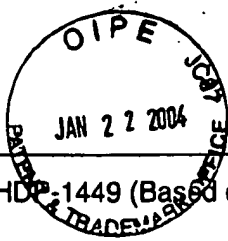
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3.		"Design of In-Pipe Inspection Vehicles for >25, >50, >150 Pipes" by Shigeo Hirose, Hidetaka Ohno, Takeo Mitsui, Kijichi Suyama, IEEE International Conference on Robotics & Automation, Detroit, MI May 1999, Pg. 2309-2314.
4.		"Limbless Locomotion: Learning to Crawl" by Kevin Dowling, IEEE International Conference on Robotics & Automation, Detroit, MI May 1999, Pg. 3001-3006.
5.		"Limbless Locomotion: Learning to Crawl with a Snake Robot" by Kevin J. Dowling, Advised by William L. Whittaker, December 1997.
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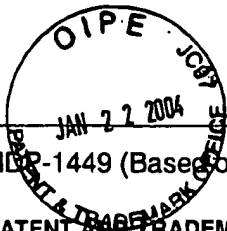
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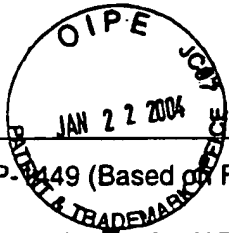
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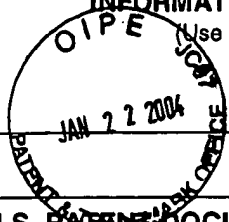
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Examiner: <i>R. Oudin</i>	Date Considered: <i>5/29/04</i>
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